

## Intermediate Parallel Programming & Cluster Computing Scientific Libraries

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Widener University



## This is an experiment!

#### It's the nature of these kinds of videoconferences that **FAILURES ARE GUARANTEED TO HAPPEN! NO PROMISES!**

- So, please bear with us. Hopefully everything will work out well enough.
- If you lose your connection, you can retry the same kind of connection, or try connecting another way.
- Remember, if all else fails, you always have the toll free phone bridge to fall back on.







- If you want to use H.323 videoconferencing for example, Polycom – then:
- If you ARE already registered with the OneNet gatekeeper, dial 2500409.
- If you AREN'T registered with the OneNet gatekeeper (which is probably the case), then:
  - Dial 164.58.250.47
  - When asked for the conference ID, enter:
     #0409#

Many thanks to Roger Holder and OneNet for providing this.







## H.323 from Internet Explorer

From a Windows PC running Internet Explorer:

- 1. You **MUST** have the ability to install software on the PC (or have someone install it for you).
- 2. Download and install the latest Java Runtime Environment (JRE) from <u>here</u> (click on the Java Download icon, because that install package includes both the JRE and other components).
- 3. Download and install this <u>video decoder</u>.
- 4. Start Internet Explorer.
- 5. Copy-and-paste this URL into your IE window: http://164.58.250.47/
- 6. When that webpage loads, in the upper left, click on "Streaming".
- 7. In the textbox labeled Sign-in Name, type your name.
- 8. In the textbox labeled Conference ID, type this: 0409
- 9. Click on "Stream this conference".
- 10. When that webpage loads, you may see, at the very top, a bar offering you options. If so, click on it and choose "Install this add-on."









There's a quick description of how to use EVO on the workshop logistics webpage.







## **Phone Bridge**

If all else fails, you can call into our toll free phone bridge: 1-800-832-0736 \* 623 2874 #

Please mute yourself and use the phone to listen.

Don't worry, we'll call out slide numbers as we go.

- Please use the phone bridge <u>ONLY</u> if you cannot connect any other way: the phone bridge is charged per connection per minute, so our preference is to minimize the number of connections.
- Many thanks to OU Information Technology for providing the toll free phone bridge.







No matter how you connect, please mute yourself, so that we cannot hear you.

- At ISU and UW, we will turn off the sound on all conferencing technologies.
- That way, we won't have problems with echo cancellation.
- Of course, that means we cannot hear questions.
- So for questions, you'll need to send some kind of text.







## **Thanks for helping!**

- OSCER operations staff (Brandon George, Dave Akin, Brett Zimmerman, Josh Alexander, Patrick Calhoun)
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- Donna Cappo, ACM
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- ID, NM, NV EPSCoR (co-sponsors)
- SC11 conference (co-sponsors)







### **Questions via Text: Piazza**

Ask questions via: http://www.piazza.com/

All questions will be read out loud and then answered out loud.

<u>NOTE</u>: Because of image-and-likeness rules, people attending remotely offsite via videoconferencing <u>CANNOT</u> ask questions via voice.







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## Outline

- Scientific Computing Pipeline
- Scientific Libraries





## **Scientific Computing Pipeline**

Real World Physics Mathematical Representation (continuous) Numerical Representation (discrete) Algorithm Implementation (program) Port (to a specific platform) Result (run) Analysis Verification Thanks to Julia Mullen of MIT Lincoln Lab for this concept.





## **Five Rules of Scientific Computing**

- 1. Know the physics.
- 2. Control the software.
- 3. Understand the numerics.
- 4. Achieve expected behavior.
- 5. Question unexpected behavior.

Thanks to Robert E. Peterkin for these.







# **Scientific Libraries**



## **Preinvented Wheels**

Many simulations perform fairly common tasks; for example, solving systems of equations: Ax = b

where **A** is the matrix of coefficients, **x** is the vector of unknowns and **b** is the vector of knowns.

$$\begin{bmatrix} a_{1,1} & a_{1,2} & a_{1,3} & \cdots & a_{1,n} \\ a_{2,1} & a_{2,2} & a_{2,3} & \cdots & a_{2,n} \\ a_{3,1} & a_{3,2} & a_{3,3} & \cdots & a_{3,n} \\ \vdots & \vdots & \ddots & \vdots \\ a_{n,1} & a_{n,2} & a_{n,3} & \cdots & a_{n,n} \end{bmatrix} \begin{bmatrix} x_1 \\ x_2 \\ x_3 \\ \vdots \\ x_n \end{bmatrix} = \begin{bmatrix} b_1 \\ b_2 \\ b_3 \\ \vdots \\ b_n \end{bmatrix}$$







## **Scientific Libraries**

Because some tasks are quite common across many science and engineering applications, groups of researchers have put a lot of effort into writing <u>scientific libraries</u>: collections of routines for performing these commonly-used tasks (for example, linear algebra solvers).

The people who write these libraries know a lot more about these things than we do.

So, a good strategy is to use their libraries, rather than trying to write our own.







## **Solver Libraries**

Probably the most common scientific computing task is solving a system of equations Ax = b

where **A** is a matrix of coefficients, **x** is a vector of unknowns, and **b** is a vector of knowns.

The goal is to solve for **x**.



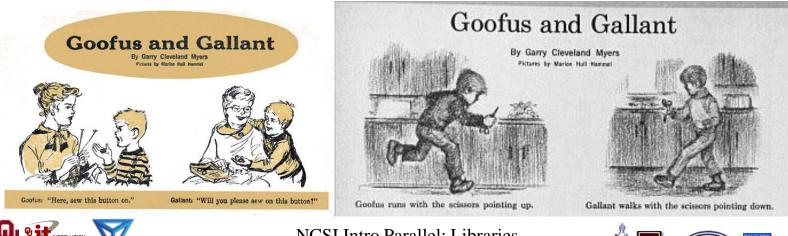


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## **Solving Systems of Equations**

#### Don'ts:

- Don't invert the matrix (x = A<sup>-1</sup>b). That's much more costly than solving directly, and much more prone to numerical error.
- <u>Don't</u> write your own solver code. There are people who devote their whole careers to writing solvers. They know a lot more about writing solvers than we do.





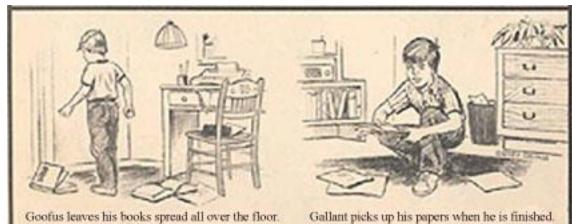


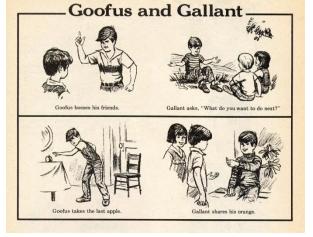




Do's:

- **Do** use standard, portable solver libraries.
- <u>Do</u> use a version that's tuned for the platform you're running on, if available.
- <u>Do</u> use the information that you have about your system of equations to pick the most efficient solver.









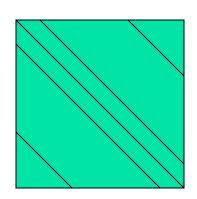


## **All About Your Matrix**

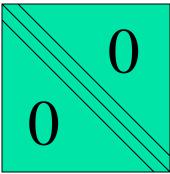
If you know things about your matrix, you maybe can use a more efficient solver.

- Symmetric:  $a_{i,j} = a_{j,i}$
- Positive definite: x<sup>T</sup>Ax > 0 for all x ≠ 0 (for example, if all eigenvalues are positive)
- Banded:

zero except on the bands



Tridiagonal:



and ...

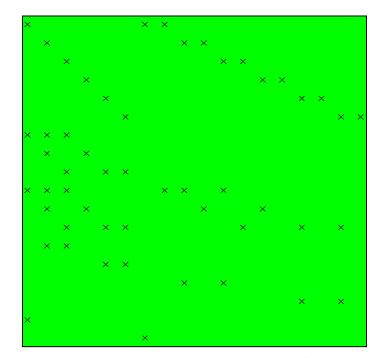






## **Sparse Matrices**

A <u>sparse matrix</u> is a matrix that has mostly zeros in it. "Mostly" is vaguely defined, but a good rule of thumb is that a matrix is sparse if more than, say, 90-95% of its entries are zero. (A non-sparse matrix is <u>dense</u>.)









## **Linear Algebra Libraries**

- BLAS <sup>[1],[2]</sup>
- ATLAS<sup>[3]</sup>
- AILAS<sup>[3]</sup>
- LAPACK<sup>[4]</sup>
- ScaLAPACK<sup>[5]</sup>
- $PETSc^{[6],[7],[8]}$









The **Basic Linear Algebra Subprograms** (BLAS) are a set of low level linear algebra routines:

- Level 1: Vector-vector (for example, dot product)
- Level 2: Matrix-vector (for example, matrix-vector multiply)
- Level 3: Matrix-matrix (for example, matrix-matrix multiply)
- Many linear algebra packages, including LAPACK, ScaLAPACK and PETSc, are built on top of BLAS.
- Most supercomputer vendors have versions of BLAS that are highly tuned for their platforms.









The <u>Automatically Tuned Linear Algebra Software</u> package (ATLAS) is a self-tuned version of BLAS (it also includes a few LAPACK routines).

- When it's installed, it tests and times a variety of approaches to each routine, and selects the version that runs the fastest.
- ATLAS is substantially faster than the generic version of BLAS.

And, it's **FREE**!









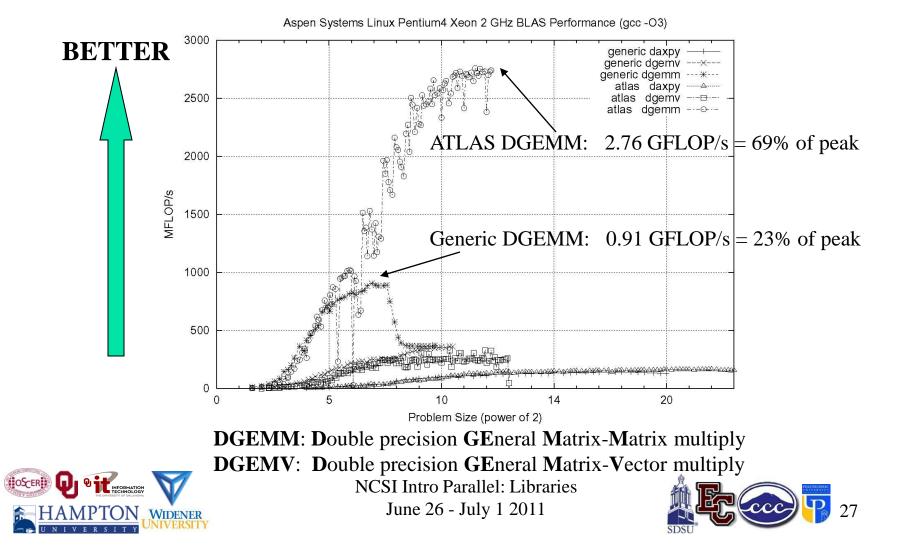
- In the past several years, a new version of BLAS has been released, developed by Kazushige Goto (currently at UT Austin).
- This version is unusual, because instead of optimizing for cache, it optimizes for the *Translation Lookaside Buffer* (TLB), which is a special little cache that often is ignored by software developers.
- Goto realized that optimizing for the TLB would be more efficient than optimizing for cache.







## **ATLAS vs. Generic BLAS**



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## LAPACK

**LAPACK** (Linear Algebra PACKage) solves dense or specialcase sparse systems of equations depending on matrix properties such as:

- Precision: single, double
- Data type: real, complex
- Shape: diagonal, bidiagonal, tridiagonal, banded, triangular, trapezoidal, Hesenberg, general dense
- Properties: orthogonal, positive definite, Hermetian (complex), symmetric, general
- LAPACK is built on top of BLAS, which means it can benefit from ATLAS.







## LAPACK Example

```
REAL, DIMENSION (numrows, numcols) :: A
REAL, DIMENSION (numrows)
                                   :: B
                                    : X
REAL, DIMENSION (numcols)
                                   :: pivot
INTEGER, DIMENSION (numrows)
INTEGER :: row, col, info, numrhs = 1
DO row = 1, numrows
  B(row) = \dots
END DO
DO col = 1, numcols
  DO row = 1, numrows
    A(row, col) = ...
  END DO
END DO
CALL sgesv(numrows, numrhs, A, numrows, pivot, &
           B, numrows, info)
&
DO col = 1, numcols
  X(col) = B(col)
END DO
```





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## **LAPACK: A Library and an API**

LAPACK is a library that you can download for free from the Web:

#### www.netlib.org

- But, it's also an Application Programming Interface (API): a definition of a set of routines, their arguments, and their behaviors.
- So, anyone can write an implementation of LAPACK.







## It's Good to Be Popular

LAPACK is a good choice for non-parallelized solving, because its popularity has convinced many supercomputer vendors to write their own, highly tuned versions.

- The API for the LAPACK routines is the same as the portable version from NetLib, but the performance can be much better, via either ATLAS or proprietary vendor-tuned versions.
- Also, some vendors have shared memory parallel versions of LAPACK.







## **LAPACK Performance**

Because LAPACK uses BLAS, it's about as fast as BLAS.

- For example, DGESV (Double precision General SolVer) on a 2 GHz Pentium4 using ATLAS gets 65% of peak, compared to 69% of peak for Matrix-Matrix multiply.
- In fact, an older version of LAPACK, called LINPACK, is used to determine the top 500 supercomputers in the world.







## **ScaLAPACK**

**ScaLAPACK** is the distributed parallel (MPI) version of LAPACK. It actually contains only a subset of the LAPACK routines, and has a somewhat awkward Application Programming Interface (API).

Like LAPACK, ScaLAPACK is also available from

www.netlib.org.









**<u>PETSc</u>** (Portable, Extensible Toolkit for Scientific Computation) is a solver library for sparse matrices that uses distributed parallelism (MPI).

- PETSc is designed for general sparse matrices with no special properties, but it also works well for sparse matrices with simple properties like banding and symmetry.
- It has a simpler, more intuitive Application Programming Interface than ScaLAPACK.







## **Pick Your Solver Package**

- Dense Matrix
  - Serial: LAPACK
  - Shared Memory Parallel: threaded LAPACK
  - Distributed Parallel: ScaLAPACK
- Sparse Matrix: PETSc







# Thanks for your attention!

# **Questions?**