Supercomputing in Plain English



Part XI: Grab Bag: Scientific Libraries, I/O, Visualization

Henry Neeman, Director

OU Supercomputing Center for Education & Research University of Oklahoma Information Technology Tuesday May 5 2009





This is an experiment!

It's the nature of these kinds of videoconferences that FAILURES ARE GUARANTEED TO HAPPEN! NO PROMISES!

So, please bear with us. Hopefully everything will work out well enough.

If you lose your connection, you can retry the same kind of connection, or try connecting another way.

Remember, if all else fails, you always have the toll free phone bridge to fall back on.





Access Grid

This week's Access Grid (AG) venue: Titan. If you aren't sure whether you have AG, you probably don't.

Tue way 5

Many thanks to John Chapman of U Arkansas for setting these up for us.





H.323 (Polycom etc)

If you want to use H.323 videoconferencing – for example, Polycom – then dial

69.77.7.203##12345

any time after 2:00pm. Please connect early, at least today.

For assistance, contact Andy Fleming of <u>KanREN</u>/Kan-ed (<u>afleming@kanren.net</u> or 785-230-2513).

KanREN/Kan-ed's H.323 system can handle up to 40 simultaneous H.323 connections. If you cannot connect, it may be that all 40 are already in use.

Many thanks to Andy and KanREN/Kan-ed for providing H.323 access.





iLinc

- We have unlimited simultaneous iLinc connections available.
- If you're already on the SiPE e-mail list, then you should already have an e-mail about iLinc. Your personal URL will always be the same.
- If you want to use iLinc, please follow the directions in the iLinc e-mail.
- For iLinc, you <u>MUST</u> use either Windows (XP strongly preferred) or MacOS X with Internet Explorer.
- To use iLinc, you'll need to download a client program to your PC. It's free, and setup should take only a few minutes.
- Many thanks to Katherine Kantardjieff of California State U Fullerton for providing the iLinc licenses.





QuickTime Broadcaster

If you cannot connect via the Access Grid, H.323 or iLinc, then you can connect via QuickTime:

rtsp://129.15.254.141/test_hpc09.sdp

We recommend using QuickTime Player for this, because we've tested it successfully.

We recommend upgrading to the latest version at:

http://www.apple.com/quicktime/

When you run QuickTime Player, traverse the menus

File -> Open URL

Then paste in the rstp URL into the textbox, and click OK.

Many thanks to Kevin Blake of OU for setting up QuickTime Broadcaster for us.





Phone Bridge

If all else fails, you can call into our toll free phone bridge:

1-866-285-7778, access code 6483137#

Please mute yourself and use the phone to listen.

Don't worry, we'll call out slide numbers as we go.

Please use the phone bridge **ONLY** if you cannot connect any other way: the phone bridge is charged per connection per minute, so our preference is to minimize the number of connections.

Many thanks to Amy Apon and U Arkansas for providing the toll free phone bridge.





Please Mute Yourself

No matter how you connect, please mute yourself, so that we cannot hear you.

At OU, we will turn off the sound on all conferencing technologies.

That way, we won't have problems with echo cancellation.

Of course, that means we cannot hear questions.

So for questions, you'll need to send some kind of text.

Also, if you're on iLinc: **SIT ON YOUR HANDS!**

Please DON'T touch ANYTHING!





Questions via Text: iLinc or E-mail

Ask questions via text, using one of the following:

- iLinc's text messaging facility;
- e-mail to sipe2009@gmail.com.

All questions will be read out loud and then answered out loud.





Thanks for helping!

- OSCER operations staff (Brandon George, Dave Akin, Brett Zimmerman, Josh Alexander)
- OU Research Campus staff (Patrick Calhoun, Josh Maxey, Gabe Wingfield)
- Kevin Blake, OU IT (videographer)
- Katherine Kantardjieff, CSU Fullerton
- John Chapman and Amy Apon, U Arkansas
- Andy Fleming, KanREN/Kan-ed
- This material is based upon work supported by the National Science Foundation under Grant No. OCI-0636427, "CI-TEAM Demonstration: Cyberinfrastructure Education for Bioinformatics and Beyond."





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Supercomputing Exercises

Want to do the "Supercomputing in Plain English" exercises?

- The first several exercises are already posted at:
 - http://www.oscer.ou.edu/education.php
- If you don't yet have a supercomputer account, you can get a temporary account, just for the "Supercomputing in Plain English" exercises, by sending e-mail to:

hneeman@ou.edu

Please note that this account is for doing the <u>exercises only</u>, and will be shut down at the end of the series.





OK Supercomputing Symposium 2009



2003 Keynote: Peter Freeman **NSF** Computer & Information Science & Engineering **Assistant Director**

2009 Keynote: Ed Seidel **Director NSF Office of** Cyberinfrastructure



2004 Keynote: Sangtae Kim **NSF Shared** Cyberinfrastructure **Division Director**





2005 Keynote: Walt Brooks NASA Advanced Supercomputing **Division Director**



2006 Keynote: Dan Atkins Head of NSF's Office of Cvberinfrastructure



2007 Keynote: Jay Boisseau Director Texas Advanced **Computing Center** U. Texas Austin

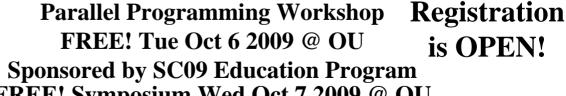


2008 Keynote: José Munoz **Deputy Office** Director/ Senior Scientific Advisor Office of Cyberinfrastructure **National Science Foundation**

FREE! Wed Oct 7 2009 @ OU http://symposium2009.oscer.ou.edu/

FREE! Tue Oct 6 2009 @ OU FREE! Symposium Wed Oct 7 2009 @ OU

Supercomputing in Plain English: Grab Bag Tuesday May 5 2009









SC09 Summer Workshops

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- At OSU Sun May 17 the May 23:
 FREE Computational Chemistry for Chemistry Educators (2010 TENTATIVE: Computational Biology)
- At OU Sun Aug 9 Sat Aug 15:
 FREE Parallel Programming & Cluster Computing

We'll alert everyone when the details have been ironed out and the registration webpage opens.

Please note that you must <u>apply</u> for a seat, and acceptance <u>CANNOT</u> be guaranteed.





SC09 Summer Workshops

- 1. May 17-23: Oklahoma State U: Computational Chemistry
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- 8. July 12-18: U Florida: Computational Thinking Grades 6-12
- 9. July 12-18: Ohio Supercomp Ctr: Computational Engineering
- 10. Aug 2-8: U Arkansas: Intro to Computational Thinking
- 11. Aug 9-15: U Oklahoma: Parallel Progrmg & Cluster Comp





Outline

- Scientific Computing Pipeline
- Scientific Libraries
- I/O Libraries
- Scientific Visualization





Scientific Computing Pipeline

Real World

Physics

Mathematical Representation (continuous)

Numerical Representation (discrete)

Algorithm

Implementation (program)

Port (to a specific platform)

Result (run)

Analysis

Verification

Thanks to Julia Mullen of MIT Lincoln Lab for this concept.





Five Rules of Scientific Computing

- 1. Know the physics.
- 2. Control the software.
- 3. Understand the numerics.
- 4. Achieve expected behavior.
- 5. Question unexpected behavior.

Thanks to Robert E. Peterkin for these.





Scientific Libraries



Preinvented Wheels

Many simulations perform fairly common tasks; for example, solving systems of equations:

$$\mathbf{A}\mathbf{x} = \mathbf{b}$$

where A is the matrix of coefficients, x is the vector of unknowns and b is the vector of knowns.

$$\begin{bmatrix} a_{1,1} & a_{1,2} & a_{1,3} & \cdots & a_{1,n} \\ a_{2,1} & a_{2,2} & a_{2,3} & \cdots & a_{2,n} \\ a_{3,1} & a_{3,2} & a_{3,3} & \cdots & a_{3,n} \\ \vdots & \vdots & \vdots & \ddots & \vdots \\ a_{n,1} & a_{n,2} & a_{n,3} & \cdots & a_{n,n} \end{bmatrix} \begin{bmatrix} x_1 \\ x_2 \\ x_3 \\ \vdots \\ x_n \end{bmatrix} = \begin{bmatrix} b_1 \\ b_2 \\ b_3 \\ \vdots \\ b_n \end{bmatrix}$$





Scientific Libraries

Because some tasks are quite common across many science and engineering applications, groups of researchers have put a lot of effort into writing *scientific libraries*: collections of routines for performing these commonly-used tasks (for example, linear algebra solvers).

The people who write these libraries know a lot more about these things than we do.

So, a good strategy is to use their libraries, rather than trying to write our own.





Solver Libraries

Probably the most common scientific computing task is solving a system of equations

$$\mathbf{A}\mathbf{x} = \mathbf{b}$$

where **A** is a matrix of coefficients, **x** is a vector of unknowns, and **b** is a vector of knowns.

The goal is to solve for \mathbf{x} .





Solving Systems of Equations

Don'ts:

- **Don't** invert the matrix $(\mathbf{x} = \mathbf{A}^{-1}\mathbf{b})$. That's much more costly than solving directly, and much more prone to numerical error.
- Don't write your own solver code. There are people who devote their whole careers to writing solvers. They know a lot more about writing solvers than we do.





Solving Do's

Do's:

- <u>Do</u> use standard, portable solver libraries.
- Do use a version that's tuned for the platform you're running on, if available.
- Do use the information that you have about your system of equations to pick the most efficient solver.



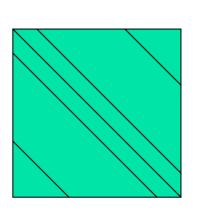


All About Your Matrix

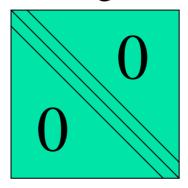
If you know things about your matrix, you maybe can use a more efficient solver.

- Symmetric: $a_{i,j} = a_{j,i}$
- Positive definite: $\mathbf{x}^T \mathbf{A} \mathbf{x} > 0$ for all $\mathbf{x} \neq 0$ (for example, if all eigenvalues are positive)
- Banded:

zero
except
on the
bands



Tridiagonal:



and ...

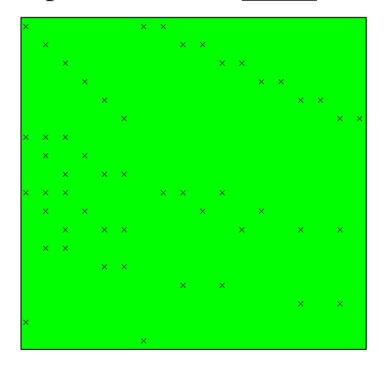






Sparse Matrices

A <u>sparse matrix</u> is a matrix that has mostly zeros in it. "Mostly" is vaguely defined, but a good rule of thumb is that a matrix is sparse if more than, say, 90-95% of its entries are zero. (A non-sparse matrix is <u>dense</u>.)







Linear Algebra Libraries

- BLAS [1],[2]
- ATLAS^[3]
- LAPACK^[4]
- ScaLAPACK^[5]
- PETSc^{[6],[7],[8]}





BLAS

The **Basic Linear Algebra Subprograms** (BLAS) are a set of low level linear algebra routines:

- Level 1: Vector-vector (for example, dot product)
- Level 2: Matrix-vector (for example, matrix-vector multiply)
- Level 3: Matrix-matrix (for example, matrix-matrix multiply)

Many linear algebra packages, including LAPACK, ScaLAPACK and PETSc, are built on top of BLAS.

Most supercomputer vendors have versions of BLAS that are highly tuned for their platforms.





ATLAS

The <u>Automatically Tuned Linear Algebra Software</u> package (ATLAS) is a self-tuned version of BLAS (it also includes a few LAPACK routines).

When it's installed, it tests and times a variety of approaches to each routine, and selects the version that runs the fastest.

ATLAS is substantially faster than the generic version of BLAS.

And, it's FREE!





Goto BLAS

In the past few years, a new version of BLAS has been released, developed by Kazushige Goto (currently at UT Austin).

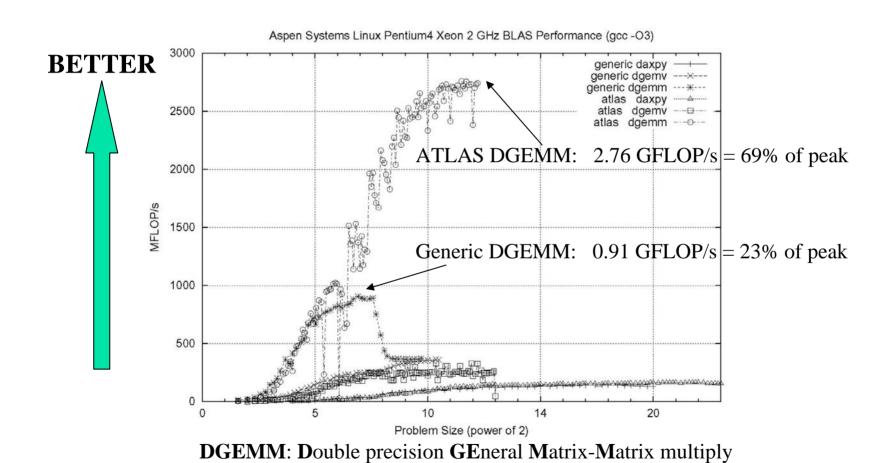
This version is unusual, because instead of optimizing for cache, it optimizes for the *Translation Lookaside Buffer* (TLB), which is a special little cache that often is ignored by software developers.

Goto realized that optimizing for the TLB would be more efficient than optimizing for cache.





ATLAS vs. Generic BLAS



DGEMV: Double precision GEneral Matrix-Vector multiply Supercomputing in Plain English: Grab Bag

Tuesday May 5 2009





LAPACK

- **LAPACK** (Linear Algebra PACKage) solves dense or special-case sparse systems of equations depending on matrix properties such as:
- Precision: single, double
- Data type: real, complex
- Shape: diagonal, bidiagonal, tridiagonal, banded, triangular, trapezoidal, Hesenberg, general dense
- Properties: orthogonal, positive definite, Hermetian (complex), symmetric, general
- LAPACK is built on top of BLAS, which means it can benefit from ATLAS.





LAPACK Example

```
REAL, DIMENSION (numrows, numcols) :: A
REAL, DIMENSION (numrows)
REAL, DIMENSION (numcols)
INTEGER,DIMENSION(numrows)
                                  :: pivot
INTEGER :: row, col, info, numrhs = 1
DO row = 1, numrows
  B(row) = ...
END DO
DO col = 1, numcols
  DO row = 1, numrows
    A(row,col) = ...
  END DO
END DO
CALL sgesv(numrows, numrhs, A, numrows, pivot, &
           B, numrows, info)
&
DO col = 1, numcols
  X(col) = B(col)
END DO
```





LAPACK: A Library and an API

LAPACK is a library that you can download for free from the Web:

www.netlib.org

But, it's also an Application Programming Interface (API): a definition of a set of routines, their arguments, and their behaviors.

So, anyone can write an implementation of LAPACK.





It's Good to Be Popular

LAPACK is a good choice for non-parallelized solving, because its popularity has convinced many supercomputer vendors to write their own, highly tuned versions.

The API for the LAPACK routines is the same as the portable version from NetLib, but the performance can be much better, via either ATLAS or proprietary vendor-tuned versions.

Also, some vendors have shared memory parallel versions of LAPACK.





LAPACK Performance

Because LAPACK uses BLAS, it's about as fast as BLAS.

For example, DGESV (Double precision General SolVer) on a 2 GHz Pentium4 using ATLAS gets 65% of peak, compared to 69% of peak for Matrix-Matrix multiply.

In fact, an older version of LAPACK, called LINPACK, is used to determine the top 500 supercomputers in the world.





ScaLAPACK

ScaLAPACK is the distributed parallel (MPI) version of LAPACK. It actually contains only a subset of the LAPACK routines, and has a somewhat awkward Application Programming Interface (API).

Like LAPACK, ScaLAPACK is also available from www.netlib.org.





PETSc

PETSc (Portable, Extensible Toolkit for Scientific Computation) is a solver library for sparse matrices that uses distributed parallelism (MPI).

PETSc is designed for general sparse matrices with no special properties, but it also works well for sparse matrices with simple properties like banding and symmetry.

It has a simpler, more intuitive Application Programming Interface than ScaLAPACK.





Pick Your Solver Package

- Dense Matrix
 - Serial: LAPACK
 - Shared Memory Parallel: threaded LAPACK
 - Distributed Parallel: ScaLAPACK
- Sparse Matrix: PETSc





I/O Libraries



I/O Challenges

I/O presents two important challenges to scientific computing:

- Performance
- Portability

The performance issue arises because I/O is much more timeconsuming than computation, as we saw in the "Storage Hierarchy" session.

The portability issue arises because different kinds of computers can have different ways of representing real (floating point) numbers.





Storage Formats

When you use a **PRINT** statement in Fortran or a **printf** in C or output to **cout** in C++, you are asking the program to output data in human-readable form:

$$x = 5$$
PRINT *, x

But what if the value that you want to output is a real number with lots of significant digits?





Data Output as Text

1.3456789E+23

When you output data as text, each character takes 1 byte.

So if you output a number with lots of digits, then you're outputting lots of bytes.

For example, the above number takes 13 bytes to output as text.

<u>Jargon</u>: Text is sometimes called <u>ASCII</u> (American Standard Code for Information Interchange).





Output Data in Binary

Inside the computer, a single precision real number (Fortran **REAL**, C/C++ **float**) typically requires 4 bytes, and a double precision number (**DOUBLE PRECISION** or **double**) typically requires 8.

That's less than 13.

Since I/O is very expensive, it's better to output 4 or 8 bytes than 13 or more.

Happily, Fortran, C and C++ allow you to output data as **binary** (internal representation) rather than as text.





Binary Output Problems

When you output data as **binary** rather than as text, you output substantially **fewer bytes**, so you save time (since I/O is very expensive) and you save disk space.

But, you pay two prices:

- Readability: Humans can't read binary.
- **Portability**: Different kinds of computers have different ways of internally representing numbers.





Binary Readability: No Problem

Readability of binary data **isn't a problem** in scientific computing, because:

- You can always write a little program to read in the binary data and display its text equivalent.
- If you have lots and lots of data (that is, MBs or GBs), you wouldn't want to look at all of it anyway.





Binary Portability: Big Problem

Binary data portability is a very big problem in scientific computing, because data that's output on one kind of computer may not be readable on another, and so:

- You can't output the data on one kind of computer and then use them (for example, visualize, analyze) on another kind.
- Some day the kind of computer that output the data will be obsolete, so there may be no computer in the world that can input it, and thus the data are lost.





Portable Binary Data

The HPC community noticed this problem some years ago, and so a number of portable binary data formats were developed. The two most popular are:

• <u>HDF</u> (Hierarchical Data Format) from the National Center for Supercomputing Applications:

http://www.hdfgroup.org/

NetCDF (Network Common Data Form) from Unidata:

http://www.unidata.ucar.edu/software/netcdf





Advantages of Portable I/O

Portable binary I/O packages:

- give you portable binary I/O;
- have simple, clear APIs;
- are available for <u>free</u>;
- run on most platforms;
- allow you to <u>annotate</u> your data (for example, put into the file the variable names, units, experiment name, grid description, etc).

Also, both HDF and netCDF support distributed parallel I/O.





Scientific Visualization



Too Many Numbers

A typical scientific code outputs lots and lots of data.

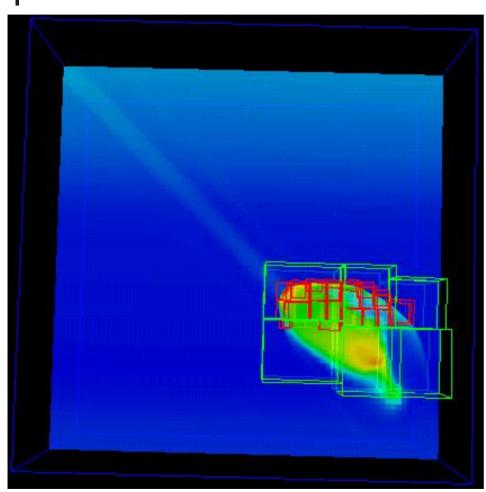
For example, the ARPS weather forecasting code, running a 5 day forecast over the continental U.S. with a resolution of 1 km horizontal and 0.25 km vertical outputting data for every hour would produce about **10 terabytes** (10¹³ bytes).

No one can look at that many numbers.





A Picture is Worth ...



... millions of numbers.

This is Comet Shoemaker-Levy 9, which hit Jupiter in 1994; the image is from 35 seconds after hitting Jupiter's inner atmosphere.^[9]







Types of Visualization

- Contour lines
- Slice planes
- Isosurfaces
- Streamlines
- Volume rendering
- ... and many others.

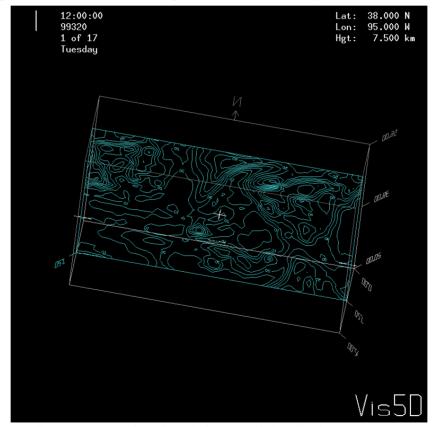
Note: except for the volume rendering, the following images were created by Vis5D,^[10] which you can download for free.





Contour Lines

This image shows *contour lines* of relative humidity. Each contour line represents a single humidity value.





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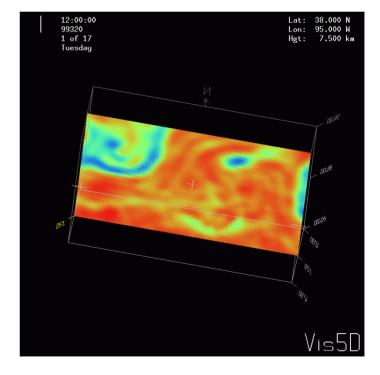


Slice Planes

A *slice plane* is a single plane passed through a 3D volume.

Typically, it is color coded by mapping some scalar variable to color (for example, low vorticity to blue, high vorticity to

red).

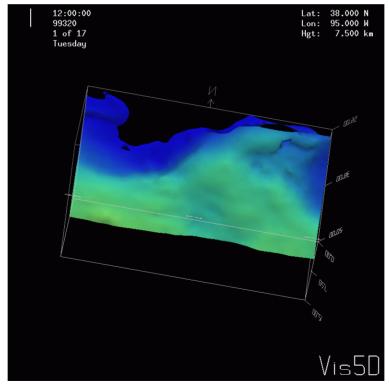






Isosurfaces

An <u>isosurface</u> is a surface that has a constant value for some scalar quantity. This image shows an isosurface of temperature at 0° Celsius, colored with pressure.



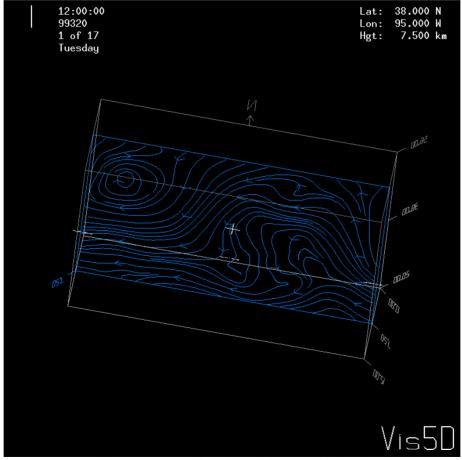






Streamlines

A streamline traces a vector quantity (for example, velocity).





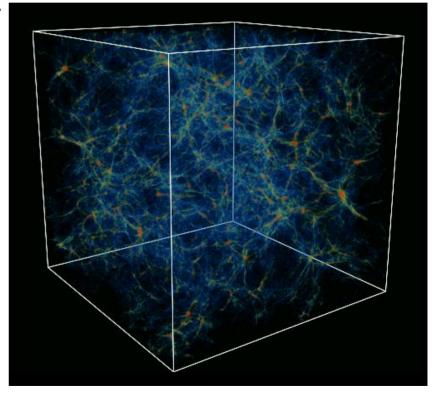




Volume Rendering

A <u>volume rendering</u> is created by mapping some variable (for example, energy) to color and another variable (for example, density) to opacity.

This image shows the overall structure of the universe.^[11]
Notice that the image looks like thick colored smoke.







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Registration **Parallel Programming Workshop** FREE! Tue Oct 6 2009 @ OU **Sponsored by SC09 Education Program** FREE! Symposium Wed Oct 7 2009 @ OU





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To Learn More Supercomputing

http://www.oscer.ou.edu/education.php





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Thanks for your attention this whole semester!

Questions?





References

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- [9] http://hneeman.oscer.ou.edu/hamr.html
- [10] http://www.ssec.wisc.edu/~billh/vis5d.html
- [11] Image by Greg Bryan, MIT.

