



Galerkin Finite Element Solution of Free-Boundary Groundwater Contaminant Model

by

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OUTLINE

- 1. Introduce free-boundary Groundwater Model tracking Contaminant Dynamics in Groundwater flowing through fissures (cracks) in rock matrix via schematic diagram.
- 2. Present coupled PDE (Partial Differential Equation) representing model.
- 3. Describe terms and parameters in PDE model.
- 4. Describe Galerkin finite element method to numerically estimate model solution.
- 5. Present graphical illustrations.
- 6. Discuss advantages of using OSCER Condor Pool and OSCER Sooner Supercomputing Facilities in obtaining numerical results, computationally.

SCHEMATIC DIAGRAM



PDE MODEL

$$\begin{cases} \partial_t C + \alpha^* \partial_z C = \beta^* \partial_z^2 C - \lambda^* C + I_R^* \Gamma(z) \\ \partial_t M = \gamma^* \left[\partial_x^2 + \partial_z^2 \right] M - \lambda^* M + A_R^* C \Gamma(x) \\ C(0, z) = C^0(z) \\ M(0, x, z) = M^0(x, z) \end{cases}$$

where

$$(t, x, z) \in [0, T_{max}] \times [0, x_{max}] \times [0, z_{max}].$$

PARAMETERS

$$\alpha^* = \frac{v}{1 + K_F/b}$$

$$\beta^* = \frac{D_W + \alpha_L v}{R_F}$$

$$\gamma^* = \frac{\theta D_W}{1 + \rho_b K_M / \theta}$$

Let

$$T = \frac{t}{T_{max}}, \ X = \frac{x}{x_{max}}, \ Z = \frac{z}{z_{max}}$$

to get

$$\begin{cases} \kappa_1 \partial_T C + \kappa_2 \alpha^* \partial_Z C = \kappa_2^2 \beta^* \partial_z^2 C - \lambda^* C + I_R^* \Gamma(Z) \\ \kappa_1 \partial_t M = \gamma^* \left[\kappa_3^2 \partial_x^2 + \kappa_2^2 \partial_z^2 \right] M - \lambda^* M + A_R^* C \Gamma(X) \\ C(0, Z) = C^0(Z) \\ M(0, X, Z) = M^0(X, Z) \end{cases}$$

where

$$\kappa_1 = \frac{1}{T_{max}}, \ \kappa_2 = \frac{1}{z_{max}}, \ \kappa_3 = \frac{1}{x_{max}}$$

and

$$(t, x, z) \in [0, 1]^3.$$

FINITE ELEMENT METHOD

Define weak solution as follows:

$$\begin{cases} \langle \kappa_1 \partial_T C + \kappa_2 \alpha^* \partial_Z C = \kappa_2^2 \beta^* \partial_z^2 C - \lambda^* C + I_R^* \Gamma(Z), \phi \rangle \\ \langle \kappa_1 \partial_t M = \gamma^* \left[\kappa_3^2 \partial_x^2 + \kappa_2^2 \partial_z^2 \right] M - \lambda^* M + A_R^* C \Gamma(X), \psi \rangle \end{cases}$$

together with initial conditions

$$\begin{cases} C(0,Z) = C^0(Z) \\ M(0,X,Z) = M^0(X,Z) \end{cases}$$

where

 ϕ piece-wise differentiable on [0, 1]

and

 ψ piece-wise differentiable on $[0, 1]^2$

NON-UNIFORM FINITE ELEMENT GRID

 $Z_0 = 0, Z_1 = \omega_Z$ $Z_j = Z_{j-1} + \rho_Z (Z_{j-1} - Z_{j-2}) \text{ for } j = 2, \cdots, ZDIM$ and

$$\begin{split} X_0 &= 0, \ X_1 = \omega_X \\ X_i &= X_{i-1} + \rho_X (X_{i-1} - X_{i-2}) \ \text{ for } i = 2, \cdots, XDIM \end{split}$$

FINITE ELEMENT APPROXIMATION

$$C(T, Z) = \sum_{i=0}^{ZDIM} \alpha_i(T) \, \varphi_i(Z)$$

and

$$M(T, X, Z) = \sum_{i=0}^{ZDIM} \sum_{j=0}^{XDIM} \beta_{ij}(T)\varphi_i(Z)\omega_j(X)$$

where $\{\varphi_i\}_{i=0}^{ZDIM}$ and $\{\omega_j\}_{j=0}^{XDIM}$ represent linear spline functions acting as approximating elements on [0, 1].

COMPUTATIONAL PROBLEM

$$\begin{cases} (\vec{\alpha}) = F(T, \vec{\alpha}) \\ \vec{\alpha}(0) = \overrightarrow{(\alpha_0)} \end{cases}$$

and

$$\begin{cases} (\vec{\beta}) = G(T, \vec{\beta}) \\ \vec{\beta}(0) = \overline{(\beta_0)} \end{cases}$$

Solved using *CVODE* from SUNDIALS from Lawrence Livermore National Laboratories (LLNL) with following values:

T _{max}	x _{max}	Z _{max}	XDIM	ZDIM
1, 2, 3, months	10 meters	10 meters	14	14

ρχ	ρ_Z	ω_X	ω_Z
0.95	0.95	0.1	0.1

GRAPHICAL ILLUSTRATIONS



Figure 2: t versus Total C - no decay



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COMPARISON OF COMPUTATION TIME

ECU UNIX	OSCER CONDOR	OSCER SOONER
5 min	2 sec	2 sec
10 hours	3 hours	32 min

SUPERCOMPUTING IS AMAZING!!

REFERENCES

[1] E. A. Sudicky & E. O. Frind, *Contaminant Transport in Fractured Porous Media: Analytic Solutions For a System of Parallel Fractures,* Water Resources Research **18(6)**, 1982.

[2] R. L. Drake & J. Chen, *Contaminant Transport in Parallel Fractured Media: Sudicky and Frind Revisited*, Submitted for Publication, 2003.

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